

Low-Rank and Predictive Process Models

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Multivariate Gaussian likelihoods for geostatistical models

- $\mathcal{L} = \{\ell_1, \ell_2, \dots, \ell_n\}$ are locations where data is observed
- $y(\ell_i)$ is outcome at the i -th location,
 $y = (y(\ell_1), y(\ell_2), \dots, y(\ell_n))^\top$
- Model: $y \sim N(X\beta, K_\theta)$
- Estimating process parameters from the likelihood:
$$-\frac{1}{2} \log \det(K_\theta) - \frac{1}{2} (y - X\beta)^\top K_\theta^{-1} (y - X\beta)$$
- K_θ is usually dense with no exploitable structure
- Bayesian inference: Priors on $\{\beta, \theta\}$
- Challenges: Storage and $\text{chol}(K_\theta) = LDL^\top$.

Prediction and interpolation

- Conditional predictive density

$$p(y(\ell_0) | y, \theta, \beta) = N \left(y(\ell_0) \mid \mu(\ell_0), \sigma^2(\ell_0) \right) .$$

- “Kriging” (spatial prediction/interpolation)

$$\begin{aligned} \mu(\ell_0) &= E[y(\ell_0) | y, \theta] = x^\top(\ell_0)\beta + k_\theta^\top(\ell_0)K_\theta^{-1}(y - X\beta) , \\ \sigma^2(\ell_0) &= \text{var}[y(\ell_0) | y, \theta] = K_\theta(\ell_0, \ell_0) - k_\theta^\top(\ell_0)K_\theta^{-1}k_\theta(\ell_0) . \end{aligned}$$

- Bayesian “kriging” computes (simulates) posterior predictive density:

$$p(y(\ell_0) | y) = \int p(y(\ell_0) | y, \theta, \beta)p(\beta, \theta | y)d\beta d\theta$$

Computational Details

- Compute the mean and variance (for any given $\{\beta, \theta\}$ and ℓ_0):

Solve for u : $K_\theta u = k_\theta(\ell_0)$;

Predictive mean: $x^\top(\ell_0)\beta + u^\top(y - X\beta)$;

Predictive variance: $K_\theta(\ell_0, \ell_0) - u^\top k_\theta(\ell_0)$.

- Compute the mean and variance (for any given $\{\beta, \theta\}$ and ℓ_0):

Cholesky: $\text{chol}(K_\theta) = LDL^\top$;

Solve for v : $v = \text{trsolve}(L, k_\theta(\ell_0))$;

Solve for u : $u = \text{trsolve}(L^\top, D^{-1}v)$;

Predictive mean: $x^\top(\ell_0)\beta + u^\top(y - X\beta)$;

Predictive variance: $K_\theta(\ell_0, \ell_0) - u^\top k_\theta(\ell_0)$.

- Primary bottleneck is $\text{chol}(\cdot)$

Burgeoning literature on spatial big data

- Low-rank models (Wahba, 1990; Higdon, 2002; Kamman & Wand, 2003; Paciorek, 2007; Rasmussen & Williams, 2006; Stein 2007, 2008; Cressie & Johannesson, 2008; Banerjee et al., 2008; 2010; Gramacy & Lee 2008; Sang et al., 2011, 2012; Lemos et al., 2011; Guhaniyogi et al., 2011, 2013; Salazar et al., 2013; Katzfuss, 2016)
- Spectral approximations and composite likelihoods: (Fuentes 2007; Paciorek, 2007; Eidsvik et al. 2016)
- Multi-resolution approaches (Nychka, 2002; Johannesson et al., 2007; Matsuo et al., 2010; Tzeng & Huang, 2015; Katzfuss, 2016)
- Sparsity: (Solve $Ax = b$ by (i) sparse A , or (ii) sparse A^{-1})
 1. Covariance tapering (Furrer et al. 2006; Du et al. 2009; Kaufman et al., 2009; Shaby and Ruppert, 2013)
 2. GMRFs to GPs: INLA (Rue et al. 2009; Lindgren et al., 2011)
 3. LAGP (Gramacy et al. 2014; Gramacy and Apley, 2015)
 4. Nearest-neighbor models (Vecchia 1988; Stein et al. 2004; Stroud et al 2014; Datta et al., 2016)

Bayesian low rank models

- A *low rank* or *reduced rank* process approximates a *parent* process over a smaller set of points (*knots*).
- Start with a *parent process* $w(\ell)$ and construct $\tilde{w}(\ell)$

$$w(\ell) \approx \tilde{w}(\ell) = \sum_{j=1}^r b_{\theta}(\ell, \ell_j^*) z(\ell_j^*) = b_{\theta}^{\top}(\ell) z,$$

where

- $z(\ell)$ is *any* well-defined process (could be same as $w(\ell)$);
- $b_{\theta}(\ell, \ell')$ is a family of basis functions indexed by parameters θ ;
- $\{\ell_1^*, \ell_2^*, \dots, \ell_r^*\}$ are the knots;
- $b_{\theta}(\ell)$ and z are $r \times 1$ vectors with components $b_{\theta}(\ell, \ell_j^*)$ and $z(\ell_j^*)$, respectively.

Bayesian low rank models (contd.)

- $\tilde{w} = (\tilde{w}(\ell_1), \tilde{w}(\ell_2), \dots, \tilde{w}(\ell_n))^T$ is represented as $\tilde{w} = B_\theta z$
- B_θ is $n \times r$ with (i, j) -th element $b_\theta(\ell_i, \ell_j^*)$
- Irrespective of how big n is, we now have to work with the r (instead of n) $z(\ell_j^*)$'s and the $n \times r$ matrix B_θ .
- Since $r \ll n$, the consequential dimension reduction is evident.
- \tilde{w} is a valid stochastic process in r -dimensions space with covariance:

$$\text{cov}(\tilde{w}(\ell), \tilde{w}(\ell')) = b_\theta^T(\ell) V_z b_\theta(\ell'),$$

where V_z is the variance-covariance matrix (also depends upon parameter θ) for z .

- When $n > r$, the joint distribution of \tilde{w} is singular.

The Sherman-Woodbury-Morrison formulas

- Low-rank dimension reduction is similar to Bayesian linear regression
- Consider a simple hierarchical model (with $\beta = 0$):

$$N(z | 0, V_z) \times N(y | B_\theta z, D_\tau),$$

where y is $n \times 1$, z is $r \times 1$, D_τ and V_z are positive definite matrices of sizes $n \times n$ and $r \times r$, respectively, and B_θ is $n \times r$.

- The low rank specification is $B_\theta z$ and the prior on z .
- D_τ (usually diagonal) has the residual variance components.
- Computing $\text{var}(y)$ in two different ways yields

$$(D_\tau + B_\theta V_z B_\theta^\top)^{-1} = D_\tau^{-1} - D_\tau^{-1} B_\theta (V_z^{-1} + B_\theta^\top D_\tau^{-1} B_\theta)^{-1} B_\theta^\top D_\tau^{-1}.$$

- A companion formula for the determinant:

$$\det(D_\tau + B_\theta V_z B_\theta^\top) = \det(V_z) \det(D_\tau) \det(V_z^{-1} + B_\theta^\top D_\tau^{-1} B_\theta).$$

Practical implementation for Bayesian low rank models

- In practical implementation, better to avoid SWM formulas.

$$\underbrace{\begin{bmatrix} D_\tau^{-1/2} y \\ 0 \end{bmatrix}}_{y_*} = \underbrace{\begin{bmatrix} D_\tau^{-1/2} B_\theta \\ V_z^{-1/2} \end{bmatrix}}_{B_*} z + \underbrace{\begin{bmatrix} e_1 \\ e_2 \end{bmatrix}}_{e_*} .$$

- $e_* \sim N(0, I_{n+r})$.
- $V_z^{1/2}$ and $D_\tau^{1/2}$ are matrix square roots of V_z and D_τ , respectively.
- If D_τ is diagonal (as is common), then $D_\tau^{1/2}$ is simply the square root of the diagonal elements of D_τ .
- $V_z^{1/2} = \text{chol}(V_z)$ is the triangular (upper or lower) Cholesky factor of the $r \times r$ matrix V_z .
- Use `backsolve` to efficiently obtain $V_z^{-1/2} z$

Practical implementation for Bayesian low rank models (contd.)

- The marginal density of $p(y_* | \theta, \tau)$ after integrating out z now corresponds to the normal linear model

$$y_* = B_* \hat{z} + e_*,$$

where \hat{z} is the ordinary least-square estimate of z .

- Use `lm` function to compute \hat{z} applying the QR decomposition to B_* .
- Thus, we estimate the Bayesian linear model

$$p(\theta, \tau) \times N(y_* | B_* \hat{z}, I_{n+r})$$

- MCMC will generate posterior samples for $\{\theta, \tau\}$.
- *Recover* the posterior samples for z from those of $\{\theta, \tau\}$:

$$p(z | y) = \int N(z | \hat{z}, M) \times p(\theta, \tau | y) d\theta d\tau$$

where $M^{-1} = V_z^{-1} + B_\theta^\top D_\tau^{-1} B_\theta$.

Predictive process models (Banerjee et al., *JRSS-B*, 2008)

- A particular low-rank model emerges by taking
 - $z(\ell) = w(\ell)$
 - $z = (w(\ell_1^*), w(\ell_2^*), \dots, w(\ell_r^*))^\top$ as the realizations of the parent process $w(\ell)$ over the set of knots $\mathcal{L}^* = \{\ell_1^*, \ell_2^*, \dots, \ell_r^*\}$,

and then taking the conditional expectation:

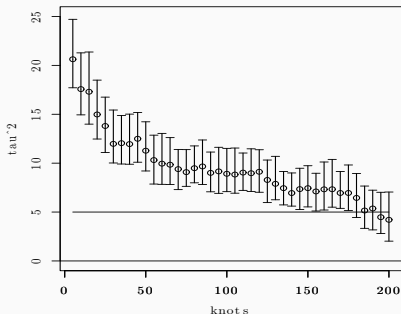
$$\tilde{w}(\ell) = E[w(\ell) | w^*] = b_\theta^\top(\ell)z .$$

- The basis functions are *automatically* derived from the spatial covariance structure of the parent process $w(\ell)$:

$$b_\theta^\top(\ell) = \text{cov}\{w(\ell), w^*\} \text{var}^{-1}\{w^*\} = K_\theta(\ell, \mathcal{L}^*) K_\theta^{-1}(\mathcal{L}^*, \mathcal{L}^*) .$$

Biases in low-rank models

- In low-rank processes, $w(\ell) = \tilde{w}(\ell) + \eta(\ell)$. What is lost in $\eta(\ell)$?



- For the predictive process,

$$\begin{aligned}\text{var}\{w(\ell)\} &= \text{var}\{E[w(\ell) | w^*]\} + E\{\text{var}[w(\ell) | w^*]\} \\ &\geq \text{var}\{E[w(\ell) | w^*]\} .\end{aligned}$$

Bias-adjusted or modified predictive processes

- $\eta(\ell)$ is a Gaussian process with covariance structure

$$\begin{aligned}\text{Cov}\{\eta(\ell), \eta(\ell')\} &= K_{\eta, \theta}(\ell, \ell') \\ &= K_{\theta}(\ell, \ell') - K_{\theta}(\ell, \mathcal{L}^*)K_{\theta}^{-1}(\mathcal{L}^*, \mathcal{L}^*)K_{\theta}(\mathcal{L}^*, \ell').\end{aligned}$$

- Remedy:

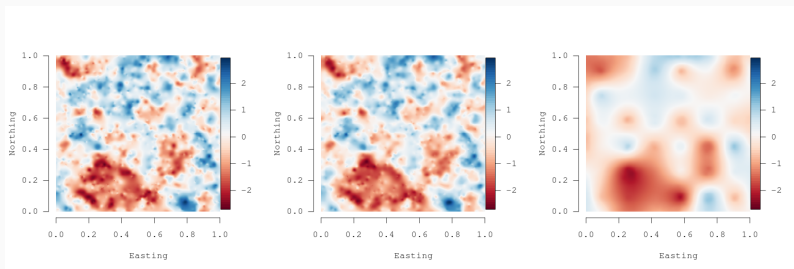
$$\tilde{w}_{\epsilon}(\ell) = \tilde{w}(\ell) + \tilde{\epsilon}(\ell),$$

where $\tilde{\epsilon}(\ell) \stackrel{\text{ind}}{\sim} N(0, \delta^2(\ell))$ and

$$\delta^2(\ell) = \text{var}\{\eta(\ell)\} = K_{\theta}(\ell, \ell) - K_{\theta}(\ell, \mathcal{L}^*)K_{\theta}^{-1}(\mathcal{L}^*, \mathcal{L}^*)K_{\theta}(\mathcal{L}^*, \ell).$$

- Other improvements suggested by Sang et al. (2011, 2012) and Katzfuss (2017).

Oversmoothing in low rank models



True w

Full GP

PPGP 64 knots

Figure: Comparing full GP vs low-rank GP with 2500 locations. Figure (1c) exhibits oversmoothing by a low-rank process (predictive process with 64 knots)